Chemotactic Movement of Ionic Liquid Droplets

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Stimuli-Controlled Fluid Movement
Stimuli-responsive materials have gained much attention recently as new means for fluid flow control within the microfluidic field. Controlling flow using conventional pumps, valves and other physical actuators can be costly and offers limited control over flow within the chip. Flow can be potentially controlled by integrating stimuli-responsive droplets into this system. This provides external control over fluid flow and allows for interesting advantages such as the potential for the droplets to act as dynamic sensing vehicles, micro-chemical reactors and micro-cargo carriers. In this work stimuli-responsive novel self-propelled droplets capable of moving at the air/liquid interface are developed and characterized.

Droplet Composition and Movement
The micro-meter sized droplets used in this project were designed to move in an open fluidic channel and were composed of the ionic liquid (IL) Trihexyl(tetradecyl)phosphonium chloride ([P{6,6,14}][Cl]). The motion of these droplets was controlled by the triggered release of the [P{6,6,14}][Cl] cation, a component of the IL and a very efficient cationic surfactant.

Once released, the surfactant lowers the surface tension of the aqueous solution, thus creating an asymmetric surface tension gradient. This leads to Marangoni like flows which drive the droplet from areas of low surface tension toward areas of high surface tension.

Single Droplet Movement
Controlled movement of a single droplet was achieved by initially filling the channels with a solution of 10^{-2} M NaOH. An acrylamide gel previously soaked in a solution of 10^{-2} M HCl was then placed at the desired destination.

Multiple Droplet Movement
Actuation of multiple droplets was achieved by initially filling the channels with a solution of 10^{-2} M NaOH. Following this 100 – 200 μl of 10^{-2} M HCl were placed at the desired destination.

Possible Applications
In principle, this effect could facilitate many applications involving smart materials, such as programmed cargo delivery within micro fluidic devices, and self-propelled micro reactors capable of performing small scale reactions at desired destinations. This could serve for the realization of very low cost/low power (ideally zero power) autonomous chemical analyzers capable of performing sophisticated microfluidic management using chemistry to drive the processes, rather than conventional pumps and valves. Incorporation of stimuli-controlled synthetic droplets in microfluidic devices offers unprecedented versatility and external flow control. We envision using these systems to create a new generation of sustainable, low-cost, externally-controlled and self-reporting fluidic systems.

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